



## PAPER

## Tetrahedral amorphous carbon resistive memories with graphene-based electrodes

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**Abstract**

Resistive-switching memories are alternative to Si-based ones, which face scaling and high power consumption issues. Tetrahedral amorphous carbon (ta-C) shows reversible, non-volatile resistive switching. Here we report polarity independent ta-C resistive memory devices with graphene-based electrodes. Our devices show ON/OFF resistance ratios  $\sim 4 \times 10^5$ , ten times higher than with metal electrodes, with no increase in switching power, and low power density  $\sim 14 \mu\text{W} \mu\text{m}^{-2}$ . We attribute this to a suppressed tunneling current due to the low density of states of graphene near the Dirac point, consistent with the current–voltage characteristics derived from a quantum point contact model. Our devices also have multiple resistive states. This allows storing more than one bit per cell. This can be exploited in a range of signal processing/computing-type operations, such as implementing logic, providing synaptic and neuron-like mimics, and performing analogue signal processing in non-von-Neumann architectures.

**1. Introduction**

There are two main types of semiconductor random access memories (RAM): static (SRAM) [1] and dynamic (DRAM) [1]. Both are volatile [1], i.e. they lose the stored information when power is off [1]. SRAMs are currently used in central processing unit (CPU) registers due to their fast write/erase times  $\sim 0.3$  ns [2]. However, typical SRAM cells comprise six transistors [1, 3] and require larger footprint [1], e.g. a cell size  $\sim 0.04 \mu\text{m}^2$  for a 6 transistors (6T) SRAM [4], compared to DRAM cells, with a footprint  $\sim 0.024 \mu\text{m}^2$  [5]. Due to this, and the scaling limit of the gate oxide in transistors, further decreasing the SRAMs footprint is difficult [1, 2]. DRAMs store information in an integrated capacitor [1]. They require periodic refreshing to regenerate the data, due to their gradual discharge as a consequence of leakage currents [2], resulting in increased power consumption, one third of which due to refreshing [6]. Flash memories are non-volatile [1], and rely on electrical charge stored by a floating gate [1], making scaling below 16 nm difficult [5], because the oxide layer, which acts as tunnel barrier [1] surrounding the floating gate, cannot be made arbitrarily thin, otherwise the charge stored in the floating gate will be lost [1]. This also limits the write and erase data rates to  $\sim 1$  ms/0.1 ms for NAND-Flash drives [2].

Resistive RAMs (RRAM) are non-volatile memories based on a change in resistance initiated by electric fields [2, 7, 8]. They are promising for next generation non-volatile memory technology, due to the high speed  $\sim$ ns [9–11], low operational power  $\sim$ pJ [9, 12], and integrability with conventional complementary metal-oxide-semiconductor, CMOS, processes [12–17]. The key performance indicators of RRAMs are [1, 12]: operation voltages; power consumption; endurance, i.e. the number of times they can be switched on/off before one of the states becomes irreversible; ON/OFF ratio,  $R_{\text{ON}}/R_{\text{OFF}}$ , and data retention, i.e. the length of time until a state changes without application of voltage.

Resistive switching (RS) in metal-oxide RRAMs based on the formation and annihilation of localized conductive filaments (CFs) has been extensively studied [12, 15, 16]. One of the most critical challenges is the electro-forming process to activate RS [2, 14–16]. A forming voltage is needed to introduce enough oxygen deficiencies to create the CF for the first time [15]. The SET and RESET processes, i.e. changes from non-conducting to conducting state and vice versa, are attributed to rupturing and re-forming of CF sections close to either top or bottom reactive metal electrodes, due to oxygen migration and electrode reduction/oxidation [15]. However, only a portion

of the oxygen deficiencies near the electrodes can be recovered during RESET, through an interfacial redox effect in the subsequent switching cycles [14–16, 18]. As a result, the forming voltage is usually much larger than the operational voltage, as it is necessary to form the biggest CF part, and  $R_{ON}/R_{OFF}$  is degraded, so that ON and OFF states become indistinguishable, since the device's resistance cannot be switched back to the initial resistive state [18]. These effects do not only lead to an increased complexity for the memory periphery circuitry due to the large forming voltage [14–16, 18], but could also limit the integration in devices with large storage capacity [16]. Therefore, research is ongoing to devise forming-free RRAMs, with  $R_{ON}/R_{OFF}$  of at least  $10^3$  [5] to keep leakage currents to a minimum [5].

RRAMs are usually integrated in circuits as crossbar arrays, i.e. the top electrode is rotated by 90 degrees with respect to the bottom one [19]. This layout offers scaling potential only limited by the minimum lithographic feature size, and the ability to generate multi-level stacking memories [15]. Crossbar arrays consist of a lower and an upper plane of parallel wires, running at right angles [20]. If both wires and spaces between them have a width  $F$ , defined as the minimum lithographic feature size [5], then the area per connection is  $a = 4F^2$  [20], where  $a = \text{cell size}/\text{half pitch}^2$  [5]. By eliminating the access transistor integrated in the RRAM crossbar it is possible to achieve the smallest theoretical cell size  $4F^2$  [21, 22]. However, a small cell size without access transistor requires  $R_{ON}/R_{OFF}$  of at least  $10^3$  to guarantee a stable and reliable performance [21, 22], which cannot be achieved with all materials and technologies [12]. RRAMs are also promising to bridge the access time gap between fast ( $\sim 60$  ns [23]), but volatile, DRAMs and non-volatile, but slow ( $\sim 20 \mu\text{s}$ – $5$  ms [23]) storage devices.

RS in amorphous carbons has been extensively studied [7–12, 24–30]. Carbon-based RS is particularly attractive for the following reasons. First, it offers high-temperature stability without degradation, with data retention demonstrated at  $300^\circ\text{C}$  for 600 mins [8], making it suitable for applications in harsh environments, such as in the automotive [31] and aerospace sectors [31]. Second, compared to metal oxides and other RS materials, carbon-based RRAMs are down-scalable, with cell sizes in the sub-100 nm range demonstrated [10], with fast ( $< 10$  ns [9, 10]) and low power ( $\sim \text{pJ}$  range [9, 10]) switching. Third,  $R_{ON}/R_{OFF}$  and threshold switching voltage ( $V_{th}$ ) can be tuned and optimized for different applications by controlling the ratio between  $\text{sp}^3$  and  $\text{sp}^2$  carbons or by the inclusion of hetero-atoms, such as oxygen [10, 32], hydrogen [26, 30] and nitrogen [24, 33], even though this makes them not mono-atomic. When the  $\text{sp}^3$  fraction is higher than 50%, amorphous carbons are called tetrahedral-amorphous carbon, ta-C [34–39].

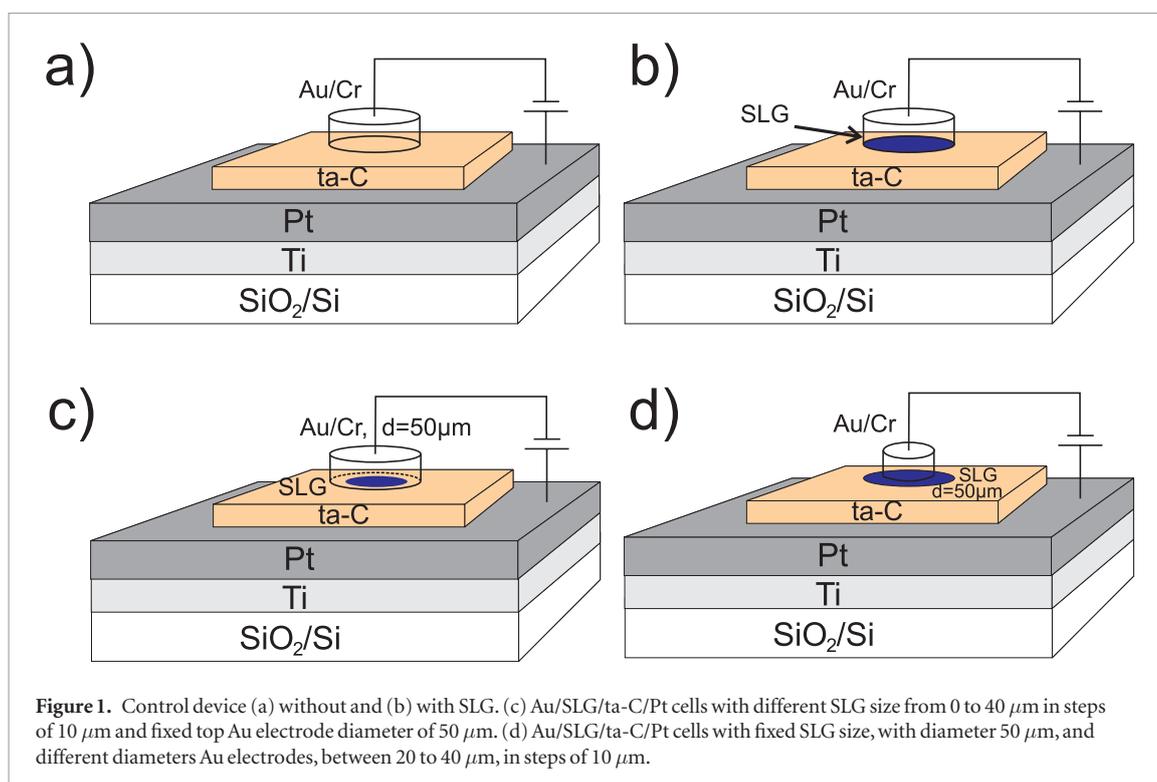
Several advantages of introducing layers of graphene into metal-oxide RRAMs have been reported

[40–42], such as suppressed tunneling current [40], monitoring oxygen movement [41], built-in selector effect acting as a switch for the RRAM cell [42], and reduced power consumption [40]. References [40–42] used chemical vapor deposition (CVD) grown graphene: single layer graphene (SLG) in [40, 41], and 3 layers of graphene in [42] for oxide based RRAMs, with a 47 times reduced power consumption [41]. In oxide based RRAMs, oxygen ions migrate under an electric field from the oxide to the top electrode (anode) leading to the formation of conductive oxygen vacancy filaments during SET, while for RESET oxygen ions move from the anode back to the oxide layer as result of the application of a field with opposite voltage polarity. References [40–42] suppressed the tunneling current through  $\text{TiO}_x$  [41] by using SLG as bottom electrode. Reference [41] monitored oxygen movement at the interface between top contact and  $\text{HfO}_x$  by inserting SLG as oxygen barrier, preventing oxygen ions to move into the electrode material [41]. Reference [42] used multilayer graphene, MLG, as a selector or switch, analogous to threshold or insulator-to-metal-transition (IMT) switches. They transferred 3 SLG on top of each other as top and bottom electrodes in a MLG/ $\text{Ta}_2\text{O}_{5-x}$ / $\text{TaO}_y$ /MLG structure. The MLG bottom electrode was heated to  $400^\circ\text{C}$  and subjected to an oxidative Ar/ $\text{O}_2$  plasma [42], and served as a selector element or switch for a RRAM cell [42].

Here we introduce SLG in ta-C based metal-insulator-metal (MIM) devices, with voltage polarity-independent RS, with SET and RESET achieved either by unipolar or bipolar switching, and forming-free RS, with  $R_{ON}/R_{OFF} \sim 10^5$ . By using electrodes based on CVD grown SLG to cover up to  $\sim 2 \times 2 \text{ cm}^2$ , we find that  $R_{ON}/R_{OFF}$  increases by one order of magnitude without increasing  $V_{th}$  and current for the SET process. We investigate the underlying mechanism by comparing a control device without SLG, and devices with fixed size of top metal electrodes and varying SLG size, as well as fixed SLG size and varying top electrode size. We use a quantum point contact (QPC) model to describe RS. The increase in  $R_{ON}/R_{OFF}$  is attributed to suppressed tunneling when using SLG-based electrodes, due to the low SLG density of states (DOS) near the Dirac point. Our data show that SLG is an excellent candidate to tackle the biggest disadvantage of crossbar arrays, i.e. leakage currents, and paves the way for replacing conventional RRAM architectures enabling scaling down to  $4F^2$  cell sizes [21, 22]. We also detect multiple resistive states, making our devices attractive for multilevel data storage, with more than one bit per cell, and increased storage density.

## 2. Experimental

We consider 3 types of devices, figure 1. The first is used as reference and has a bottom electrode (Ti/Pt)/ta-C/top electrode (Cr/Au) structure either without, figure 1(a), or with SLG inserted between ta-C and top electrode,



**Figure 1.** Control device (a) without and (b) with SLG. (c) Au/SLG/ta-C/Pt cells with different SLG size from 0 to 40  $\mu\text{m}$  in steps of 10  $\mu\text{m}$  and fixed top Au electrode diameter of 50  $\mu\text{m}$ . (d) Au/SLG/ta-C/Pt cells with fixed SLG size, with diameter 50  $\mu\text{m}$ , and different diameters Au electrodes, between 20 to 40  $\mu\text{m}$ , in steps of 10  $\mu\text{m}$ .

where SLG has the same size as the top electrode, figure 1(b). The second and third have either larger top contact compared to SLG, figure 1(c), or smaller, figure 1(d). In each of them a 10 nm Ti adhesion layer and a 40 nm Pt layer are sputtered on the  $\text{SiO}_2$ (285 nm)/Si substrate. A 15 nm ta-C film is then deposited through a stainless steel shadow mask using a single-bend filtered cathodic vacuum arc [35]. This thickness is chosen to avoid delamination from the Pt substrate.

The ta-C film is characterized by multiwavelength Raman spectroscopy at 244, 325, 457, 514.5 and 633 nm using a Renishaw InVia spectrometer equipped with a Leica DM LM microscope. All carbons show common features in their Raman spectra in the 800–2000  $\text{cm}^{-1}$  region, the so called G and D peaks, which lie at  $\sim 1560$  and  $1360 \text{ cm}^{-1}$  for visible excitation, and the T peak at  $\sim 1060 \text{ cm}^{-1}$ , which can be detected for UV excitation [43, 44]. The G peak is due to the bond stretching of all pairs of  $\text{sp}^2$  atoms in both rings and chains [39]. The D peak is due to the breathing modes of  $\text{sp}^2$  atoms in rings [39, 45, 46]. The T peak is assigned to the C–C  $\text{sp}^3$  vibrations [47, 48]. An empirical three-stage model was developed to describe the Raman spectra of carbon films measured at any excitation energy [39, 43, 49]. The evolution of the spectra is understood by considering an amorphisation trajectory, starting from graphite. The main factor affecting peaks position, width and intensity is the clustering of the  $\text{sp}^2$  phase. This can in principle vary independently from the  $\text{sp}^3$  content, so that for a given  $\text{sp}^3$  content and excitation energy, we can have a number of different Raman spectra [39, 43] or, equivalently, similar Raman spectra for different  $\text{sp}^3$  contents [39, 43]. For UV excitation, an increase in clustering lowers the G peak position, Pos(G). However, in visible Raman the G peak

does not depend monotonically on cluster size. If two samples have similar Pos(G) in visible Raman, but different ones in UV Raman, the sample with the lower Pos(G) in the UV has higher  $\text{sp}^2$  clustering [39, 43]. A multi-wavelength Raman analysis is thus important to fully characterize the samples. A very useful parameter is the G peak dispersion, Disp(G), i.e. the slope of the line connecting Pos(G) measured at different excitation wavelengths [43]. Another useful parameter is the full width at half maximum of the G peak, FWHM(G). Both FWHM(G) and Disp(G) increase with disorder, at every excitation wavelength [39, 43]. Thus, Disp(G) allows one to estimate the Young's modulus [43], density [50] and  $\text{sp}^3$  content [34, 43, 50]. Figure 2 plots representative spectra measured on the 15 nm thick ta-C film on Pt/Ti/ $\text{SiO}_2$ /Si. This gives: Disp(G)  $\sim 0.33 \text{ cm}^{-1} \text{ nm}^{-1}$ ,  $I(\text{T})/I(\text{G}) \sim 0.32$ , corresponding to  $\text{sp}^3 \sim 60\%$ .

In a control device, a Au(60 nm)/Cr(3 nm) electrode is placed on the ta-C by thermal evaporation and lift-off, figure 1(a). Inert metals, such as Pt and Au, are used as electrodes to ensure that the RS in the ta-C based cell does not result from the diffusion of metal ions and metal filament formation into the ta-C or from interfacial redox effects of the electrodes, unlike RS in oxides [14–16, 18]. RS in ta-C was assigned to the formation of an  $\text{sp}^2$  CF in the  $\text{sp}^3$  matrix between top and bottom electrodes, driven by Joule heating [10, 30, 51]. In reference [24] we studied the influence of nitrogen implantation on RS in ta-C. This leads to an increase in  $\text{sp}^2$  bonding, consistent with previous reports [52–54], and a reduction in RS voltage by up to  $\sim 60\%$ . In reference [10] we reported switching times  $\sim 50 \text{ ns}$  for SET and  $\sim 4 \text{ ns}$  for RESET in ta-C based devices, with an endurance  $> 10^4$ . The involvement of trapping and de-trapping of electrons

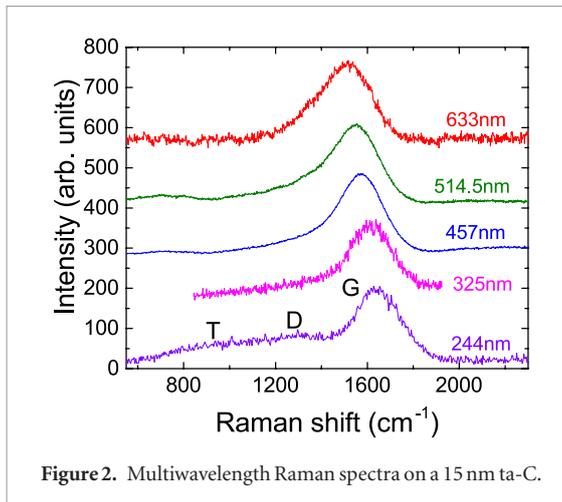


Figure 2. Multiwavelength Raman spectra on a 15 nm ta-C.

in defect states is unlikely [10, 24], because the traps would first need to be filled by electrons before these can contribute to the current.

Au is used to form the metal/SLG contact, because the SLG DOS is unchanged when Au is placed on top. Indeed, reference [55] reported that the quantum capacitance of a SLG device with Au electrodes in a transfer length method configuration exhibits an ambipolar behavior, suggesting that Au has little influence on the SLG DOS.

SLG is grown by CVD on a 35  $\mu\text{m}$ -Cu foil loaded into a hot wall tube furnace as for reference [56]. The Cu foil is annealed in a hydrogen atmosphere ( $\text{H}_2$ , 20 sccm) at 1000  $^\circ\text{C}$  for 30 mins to reduce the Cu oxide component [56] and to increase the Cu grain size [56]. Growth is initiated by adding 5 sccm  $\text{CH}_4$  to the  $\text{H}_2$  flow. After 30 min, the substrate is cooled in vacuum (1 mTorr) to RT and then unloaded from the reactor. Figure 3(a) plots the Raman spectrum of the as-grown material on Cu, after the non-flat PL background of Cu is removed [57]. The 2D peak can be fitted with a single Lorentzian with  $\text{FWHM}(2\text{D}) \sim 40 \text{ cm}^{-1}$  indicating SLG [58].  $\text{Pos}(G)$  and  $\text{FWHM}(G)$  are  $\sim 1587$  and  $\sim 21 \text{ cm}^{-1}$ , respectively, and the 2D to G intensity and area ratios are  $I(2\text{D})/I(G) \sim 3$  and  $A(2\text{D})/A(G) \sim 5.6$ , with  $I(D)/I(G) \sim 0.14$ , corresponding to a defect concentration  $n_D \sim 3.4 \times 10^{10} \text{ cm}^{-2}$  [59, 60]. SLG is then placed on the ta-C by a polymethyl methacrylate (PMMA)-based wet transfer [61, 62]. To monitor the SLG quality before and after transfer, the ta-C background signal is measured under the same conditions and subtracted point-by-point by using the Si substrate signal as reference. Figure 3(b) shows that, after transfer,  $\text{Pos}(G)$  and  $\text{FWHM}(G)$  are  $\sim 1582$  and  $\sim 16 \text{ cm}^{-1}$ , while  $I(2\text{D})/I(G)$  and  $A(2\text{D})/A(G)$  are  $\sim 4.9$  and 8.5, respectively.  $\text{Pos}(2\text{D})$  and  $\text{FWHM}(2\text{D})$  are  $\sim 2689$  and  $30 \text{ cm}^{-1}$ . These data point to very small doping  $\ll 100 \text{ meV}$  [59, 63, 64] of SLG on ta-C.  $I(D)/I(G) \sim 0.1$  indicates that no significant amount of defects has been introduced during transfer.

Our devices are prepared with Au/Cr top electrodes diameters of 10, 20, 30, 40 and 50  $\mu\text{m}$ , defined

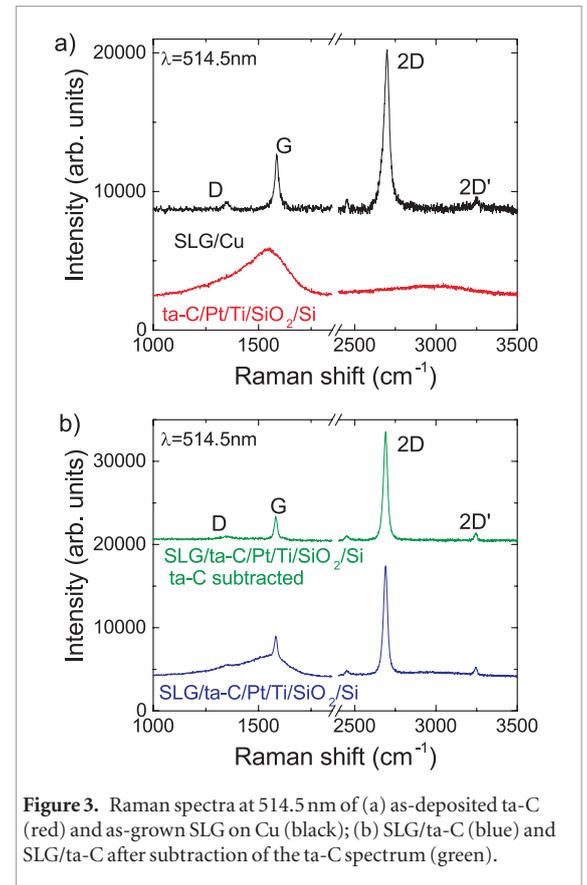


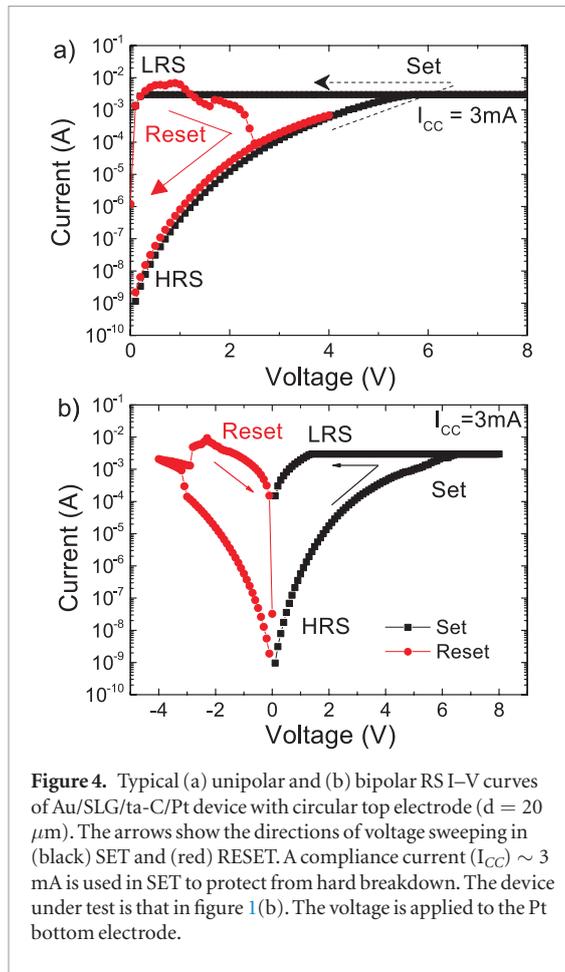
Figure 3. Raman spectra at 514.5 nm of (a) as-deposited ta-C (red) and as-grown SLG on Cu (black); (b) SLG/ta-C (blue) and SLG/ta-C after subtraction of the ta-C spectrum (green).

by lithography.  $\text{O}_2$  plasma reactive-ion etching (RIE) is then used to remove any SLG regions left uncovered. As a result, SLG has the same shape as the electrodes on top of it, figure 1(b). This is one type of reference sample. The second and third set of devices are prepared with two lithography steps to shape the SLG and metal electrodes size. In one case, SLG is shaped by lithography into circular areas with fixed 50  $\mu\text{m}$  diameter, followed by the fabrication of Au(60 nm)/Cr(3 nm) top electrodes, also having circular shapes, but with diameters of 20, 30, 40 and 50  $\mu\text{m}$ , directly on top of SLG by thermal evaporation and lift-off, figure 1(c). In the other devices, SLG is shaped into different circular areas with varying diameters starting from no SLG to 10, 20, 30, 40 and 50  $\mu\text{m}$ , while the top Au electrode diameter is kept at 50  $\mu\text{m}$ , figure 1(d).

To characterize the devices electrically, I–V curves are recorded on a CascadeMicrotech probe station using a Keysight B1500A semiconductor analyzer. Ta-C is deposited through a shadow mask. This enables the areas where Pt is protected by the shadow mask to be accessible to the probes.

### 3. Results and discussion

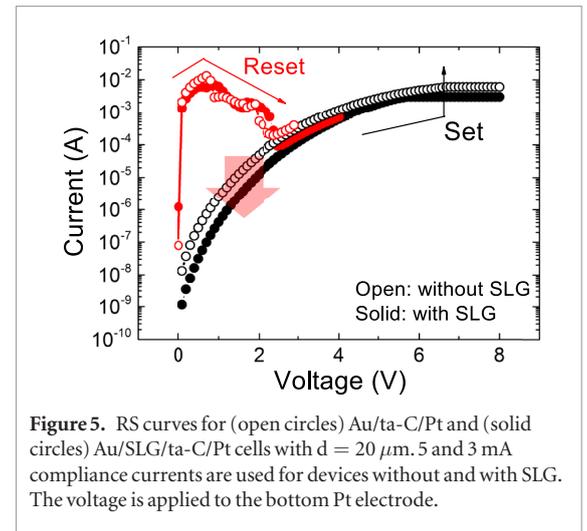
Figure 4 plots typical RS I–V curves for an Au/SLG/ta-C/Pt device ( $d = 20 \mu\text{m}$ ) operated in unipolar mode, i.e. with only positive voltage sweep, figure 4(a), and bipolar, where opposite voltage polarities are used for SET and RESET, figure 4(b). Figure 4(b) shows that RS is independent on polarity. The device



**Figure 4.** Typical (a) unipolar and (b) bipolar RS I–V curves of Au/SLG/ta-C/Pt device with circular top electrode ( $d = 20 \mu\text{m}$ ). The arrows show the directions of voltage sweeping in (black) SET and (red) RESET. A compliance current ( $I_{CC} \sim 3 \text{mA}$ ) is used in SET to protect from hard breakdown. The device under test is that in figure 1(b). The voltage is applied to the Pt bottom electrode.

is initially in a high resistance state (HRS) and can be set to a low resistance state (LRS) by sweeping the DC voltage from 0 to 8 V, and reset back by a sweeping the voltage from 0 to 4 V. A 3 mA compliance current, i.e. a fixed maximum limit of current, is also used in the SET process to protect the device from irreversible or hard breakdown, where the CF would be too thick to be ruptured, thus making RESET impossible. Figure 4 also shows  $R_{ON}/R_{OFF} \sim 4 \cdot 10^5$  at 0.2 V, without electro-forming, unlike metal oxides [14–16, 18].

RS in ta-C is different from metal oxides, where it is assigned to electrochemical processes near the interface between oxide and electrode [14–16, 18] and depends on polarity [15, 16]. Given the single elemental nature of our devices, in our case RS originates from the structural changes inside the ta-C, with no forming process. Forming-free RS was reported in organic materials, such as poly(ethylene glycol dimethacrylate) (PEGDMA) [65] and assigned to  $sp^2$  CFs [65]. In our devices, the formation of a  $sp^2$  CF during SET is attributed to electric field induced migration of  $sp^2$  carbons and clusters in the surrounding  $sp^3$  matrix [7, 8, 25, 29, 30] and the transition from  $sp^3$  to  $sp^2$  [10] due to local current annealing [9, 10]. The CF dissolution in RESET is most likely caused by a thermal fuse effect, due to the Joule heat generated by high local current density [7, 8, 10, 25, 29, 30, 51], with  $T \sim 1600 \text{K}$ , as derived by atomistic simulations [10]. Reference [10] pointed out the importance



**Figure 5.** RS curves for (open circles) Au/ta-C/Pt and (solid circles) Au/SLG/ta-C/Pt cells with  $d = 20 \mu\text{m}$ . 5 and 3 mA compliance currents are used for devices without and with SLG. The voltage is applied to the bottom Pt electrode.

of heat dissipation from top and bottom electrodes. This helps the SET process by inducing the formation of chains of  $sp^2$  clusters, which eventually merge to form a single conjugated CF, while heat dissipation in the CF direction, as well as T gradients, are crucial for RESET [10]. RS in ta-C is also different from phase change materials (PCM), where a change from amorphous to crystalline and back is achieved by heating [66, 67], while local melting and rapid quenching form amorphous regions [66, 67].

In order to investigate the influence of the interfacial SLG, the RS characteristics of the devices with and without SLG are compared in figure 5. Although the two devices show similar RS behavior, that with SLG has lower current by a factor  $\sim 4$  at the HRS, especially for voltages  $< 0.5 \text{V}$ . To clarify the reason of the decreased HRS current, Au/SLG/ta-C/Pt cells with different  $d_{Au}$  and  $d_{SLG}$  are tested. Figure 6(a) plots the I–V characteristics of devices with fixed  $d_{Au}$  and different  $d_{SLG}$ . We keep  $d_{Au} = 50 \mu\text{m}$ , while  $d_{SLG}$  ranges from 40 to 0  $\mu\text{m}$ , i.e. no SLG, in steps of 10  $\mu\text{m}$ . In order to ensure that SLG is fully covered by Au and minimize the effect of misalignment between the two steps of lithography,  $d_{SLG}$  is kept  $< d_{Au}$ . Figure 6(a) shows that the HRS current decreases with increasing  $d_{SLG}$ . Figure 6(c) plots the current at 0.2 V for increasing  $d_{SLG}$  with fixed  $d_{Au} = 50 \mu\text{m}$ . The HRS current decreases for increasing  $d_{SLG}$ , reducing the current by about one order of magnitude for  $d_{SLG} = 40 \mu\text{m}$ , with  $d_{SLG} = 10 \mu\text{m}$  already showing a pronounced effect with a reduction in current by a factor of 4, figure 6(c). This leads to an increase in  $R_{ON}/R_{OFF}$  by one order of magnitude from  $\sim 10^5$  to  $\sim 10^6$ . Figure 6(b) plots the I–V curves for  $d_{SLG} = 50 \mu\text{m}$  and different  $d_{Au}$ . When  $d_{Au}$  changes from 40 to 20  $\mu\text{m}$ , the current does not change significantly.

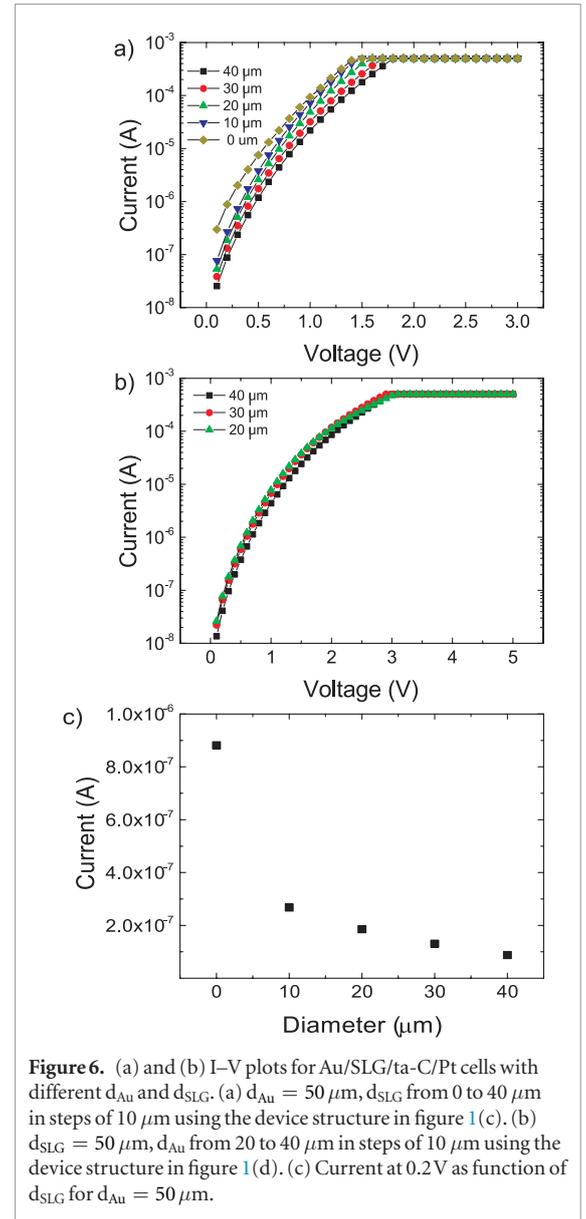
These results indicate that (1) the change of the series resistance due to a different Au/SLG contact area hardly influences the HRS current, and (2) SLG leads to a  $R_{ON}/R_{OFF}$  increase by an order of magnitude. Additionally, the Au electrode has weak interaction with SLG, i.e. it does not change the SLG DOS [55]. We attribute the decreased HRS current of the SLG-based

device to suppressed tunneling current from ta-C to the contact, due to the low DOS of undoped SLG near the Dirac point. Indeed, Raman measurements on the transferred SLG show that it has very low doping, with  $E_F \ll 100$  meV.

We analyze 15 different devices with SLG-based and metal electrodes to investigate the SLG influence on (a)  $R_{ON}/R_{OFF}$ , (b) operation voltage, (c) current and (d) device-to-device variation. The results are summarized in figure 7. This further verifies that SLG suppresses the HRS current at low bias  $< 0.5$  V, with an order of magnitude increase of  $R_{ON}/R_{OFF}$ . Having a high  $R_{ON}/R_{OFF}$  is a key requirement for scaling cell sizes down to  $4F^2$  [21, 22], as this allows one to remove the access transistor [19, 21, 22]. At the same time, the switching voltage and current where the resistance shows an abrupt change in the I–V curve, indicating the change from HRS to LRS, are the same for devices with and without SLG, resulting in a power density  $\sim 14 \mu\text{W} \mu\text{m}^{-2}$  for the SET process. This points to the voltage drop on SLG being negligible with no change in operational power density. This can be understood by considering the series connection of the SLG quantum capacitance, i.e. the additional series capacitance related to the DOS [68], and the ta-C capacitance. The real part of the dielectric function of ta-C,  $\epsilon_1$  can be related to the refractive index as well as an inter-band effective electron mass,  $m^*/m = 0.87$  [50], with  $n^2(0) = \epsilon_1(0) = (1 - m^*/m)^{-1}$  and  $n$  the refractive index [50]. We have  $\epsilon_1(0) \sim 7.7$  for ta-C using  $m^*/m = 0.87$ . Therefore the capacitance of the  $d = 15$  nm ta-C used here is:  $C/A = \epsilon_1(0) \cdot \epsilon_0/d \sim 0.45 \mu\text{F} \text{cm}^{-2}$ . This is at least one order of magnitude smaller than the minimum quantum capacitance of SLG near the Dirac point, which is usually  $> 2 \mu\text{F} \text{cm}^{-2}$  [68]. From our Raman measurements  $E_F \ll 100$  meV. This corresponds to a charge carrier concentration  $n_{ch} = (E_F/\hbar v_F)^2 (\pi)^{-1} \ll 6 \times 10^{11} \text{cm}^{-2}$ . With this, the SLG quantum capacitance can be estimated as  $C_Q = 2e^2 \sqrt{n_{ch}}/\hbar v_F \sqrt{\pi} \sim 2 \mu\text{F} \text{cm}^{-2}$  [68], where  $e = 1.6 \cdot 10^{-19} \text{C}$  is the elementary charge, and  $v_F = 1.1 \cdot 10^6 \text{m s}^{-1}$  is the SLG Fermi velocity [69, 70]. Since these two capacitances are in series, the larger voltage drop is at the smallest one, i.e. 82% of the voltage drop is at the ta-C layer.

Table 1 compares literature data [7, 9, 25, 26, 30, 32, 33, 71] on  $R_{ON}/R_{OFF}$  and power density for devices based on amorphous carbon (a-C), ta-C, hydrogenated amorphous carbon (a-C:H) and amorphous carbon oxide (a-CO<sub>x</sub>). This shows that our devices have better  $R_{ON}/R_{OFF}$  than those based on layered materials [12], with very low power consumption, proving that SLG is beneficial for optimizing the device performance.

The RS characteristics of ta-C based MIM devices can be analyzed by using the QPC model based on the Landauer theory for mesoscopic conductors [72–74]. This is built on the idea that the CF behaves as a quantum wire [72–74], and was used to describe RS in oxides [75]. It considers the CF as a

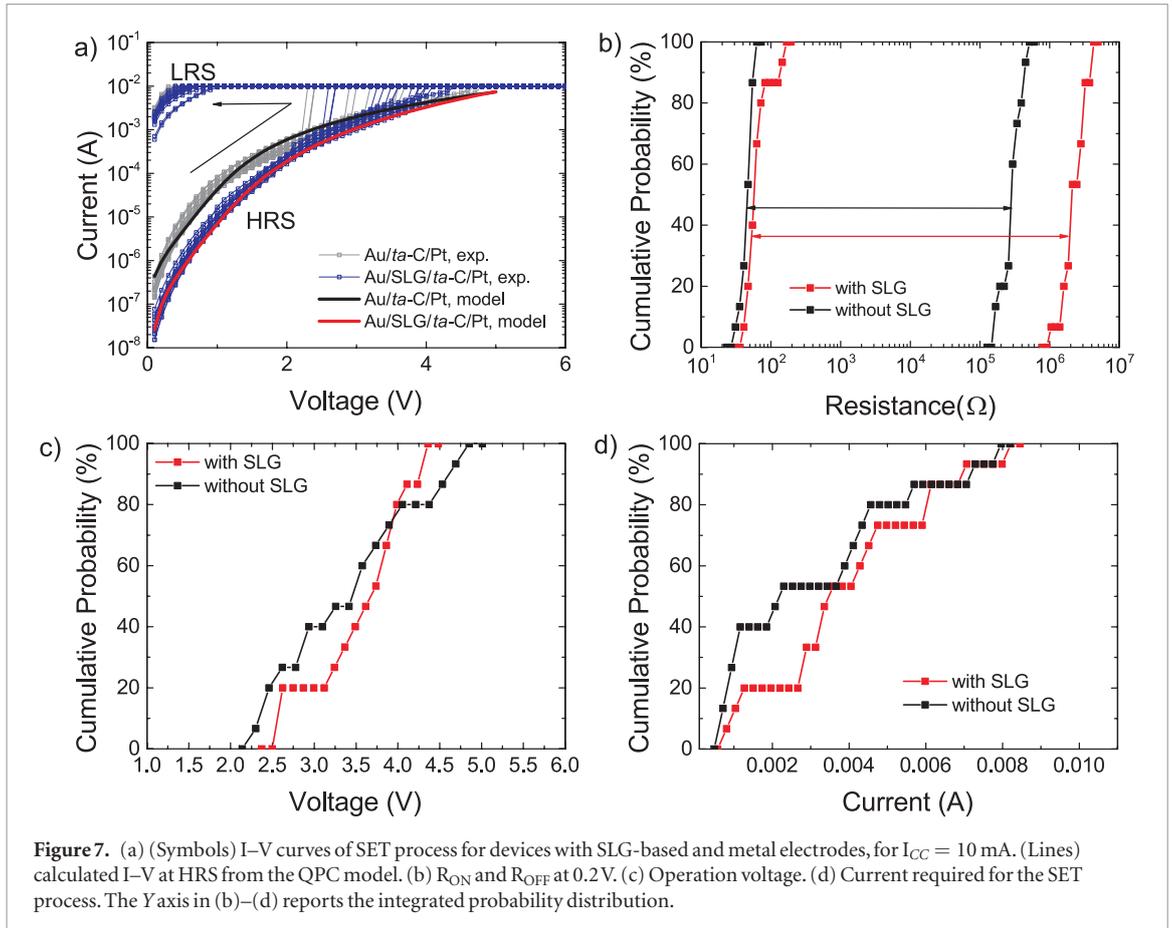


**Figure 6.** (a) and (b) I–V plots for Au/SLG/ta-C/Pt cells with different  $d_{Au}$  and  $d_{SLG}$ . (a)  $d_{Au} = 50 \mu\text{m}$ ,  $d_{SLG}$  from 0 to 40  $\mu\text{m}$  in steps of 10  $\mu\text{m}$  using the device structure in figure 1(c). (b)  $d_{SLG} = 50 \mu\text{m}$ ,  $d_{Au}$  from 20 to 40  $\mu\text{m}$  in steps of 10  $\mu\text{m}$  using the device structure in figure 1(d). (c) Current at 0.2 V as function of  $d_{SLG}$  for  $d_{Au} = 50 \mu\text{m}$ .

**Table 1.** Power density and  $R_{ON}/R_{OFF}$  for carbon-based RRAMs.

Device structure	Power density ( $\mu\text{W} \mu\text{m}^{-2}$ )	$R_{ON}/R_{OFF}$
W/a-C/Pt [7]	$1.3 \times 10^3$	$1 \times 10^3$
W/a-C/W [9]	$4.2 \times 10^2$	$1 \times 10^4$
CNT/a-C/CNT [25]	$8.2 \times 10^7$	$1 \times 10^1$
TiN/a-C:H/Pt [26]	$6.4 \times 10^5$	$1 \times 10^2$
TiN/a-C:H/Pt [30]	$6.3 \times 10^2$	$1 \times 10^2$
W/a-CO <sub>x</sub> /Pt [32]	$2.3 \times 10^4$	$1 \times 10^3$
Cu/a-C:N/Pt [33]	$1.4 \times 10^0$	$1 \times 10^2$
W/ta-C/Pt [71]	$3.8 \times 10^5$	$1 \times 10^4$
Au/SLG/ta-C/Pt [this work]	$1.4 \times 10^1$	$1 \times 10^5$

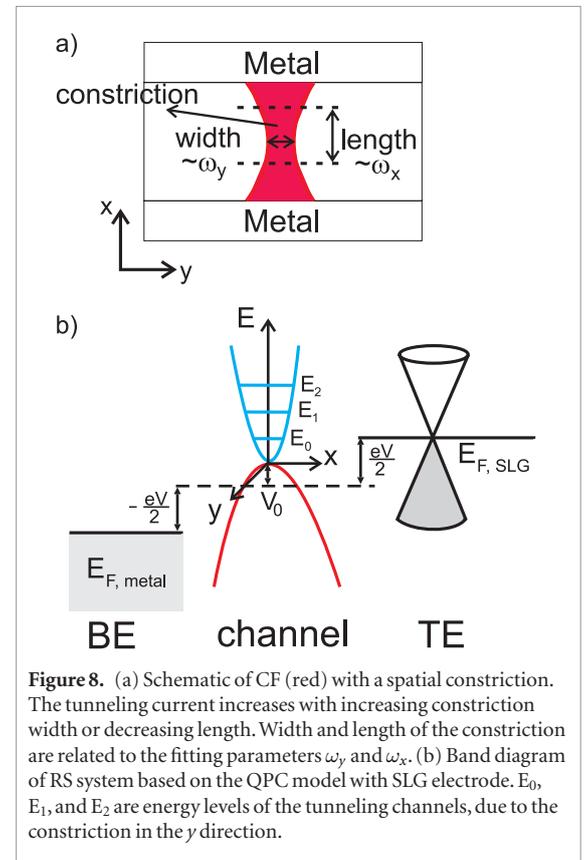
1-dimensional parabolic potential well with an additional parabolic potential barrier along the filament, defining a saddle surface in the  $x, y, E$  space given by  $E(x, y) = eV_0 - 0.5m\omega_x^2x^2 + 0.5m\omega_y^2y^2$ ,  $V_0$  describes the  $E_F$  position in the constriction and  $\omega_x$  (Hz) and  $\omega_y$  (Hz) are related to and determine the constriction length and width [72, 73].



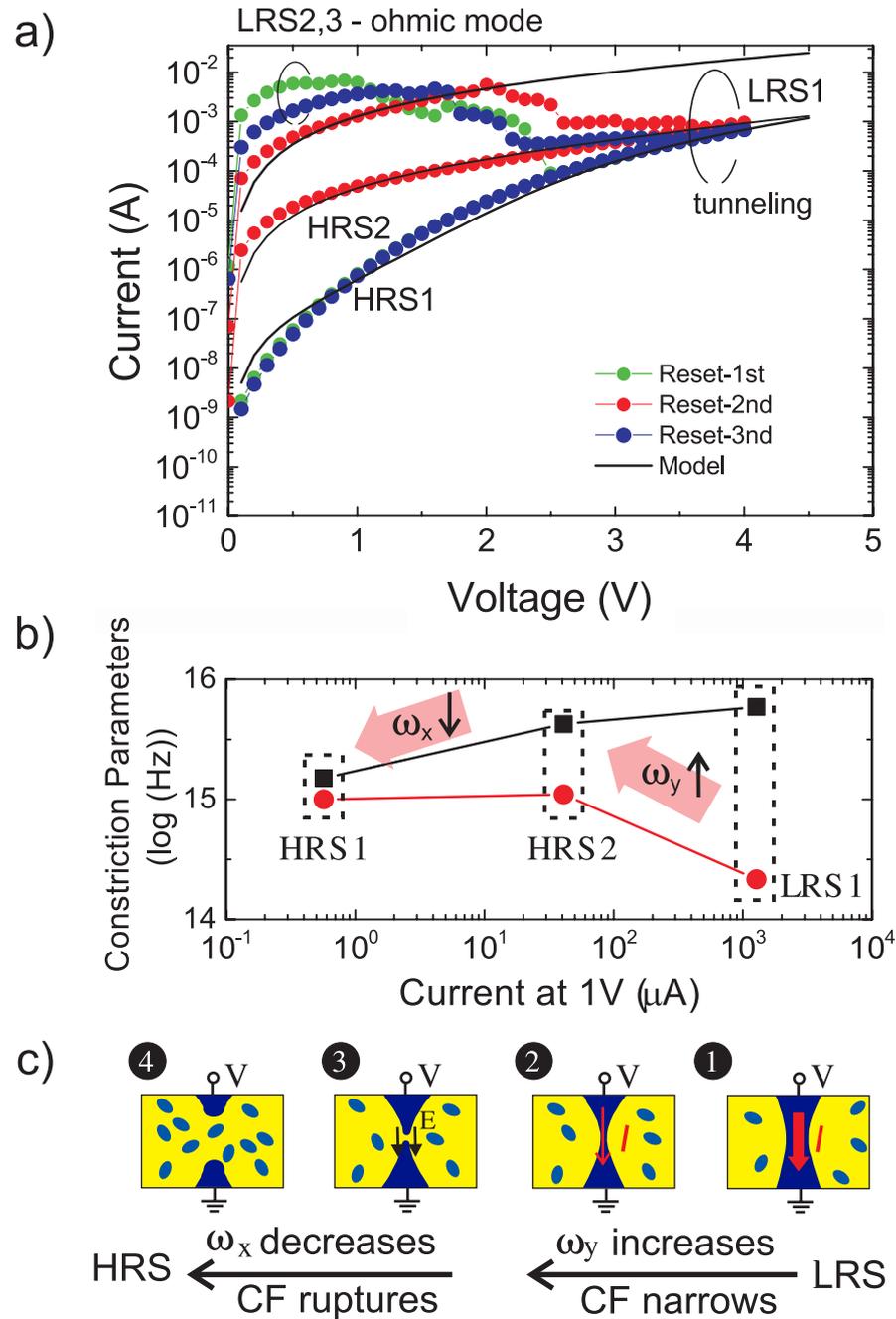
This model assumes a parabolic potential shape, because it is a good approximation for the saddle-point potential distribution between adjacent conducting sites [74, 76]. The saddle surface with a parabolic potential models the CF constriction in the  $y$ -direction and the parabolic potential barrier in the  $x$ -direction [73]. In this model, the current flowing through the CF is limited by a constriction in the middle of the CF as for figure 8(a). Thus, the change of the resistive states can be attributed to the widening or narrowing/rupturing of the constriction. The HRS is described by a tunnel barrier height, above the energy of the injected electrons, while for LRS a transmission coefficient  $T(E) \sim 1$  is assumed, describing the low resistance and high conductance state [74]. Figure 8(b) depicts the energy diagram of the RS system under a given applied voltage,  $V$ . The constriction leads to a series of tunneling channels with discrete energy levels  $E_n$ . The total tunneling current,  $I_{tot}$ , is equal to the sum of the tunneling currents in each channel [72, 73]:

$$I_{tot}(V) \sim \int_{-eV/2}^{eV/2} \text{DOS}_B \left( E + \frac{eV}{2} \right) \text{DOS}_T \left( E - \frac{eV}{2} \right) T(E) dE \quad (1)$$

where  $T(E) = \sum_{j=0}^N \{ 1 + \exp[-2\pi(E - E_j)/\hbar\omega_x] \}^{-1} = \sum_{j=0}^N T_n(E)$ ,  $\text{DOS}_B(E)$  and  $\text{DOS}_T(E)$  are the DOS of the bottom and top electrodes,  $T(E)$  is the total transmission probability of electrons,  $j$  is the number of channels, and  $T_j(E)$  is the transmission probability



of the  $j$ th channel. The tunneling current at a given voltage is thus determined by  $\text{DOS}_B(E)$ ,  $\text{DOS}_T(E)$ , and  $T(E)$ . While  $\text{DOS}_B(E)$  and  $\text{DOS}_T(E)$  are inherent



**Figure 9.** (a) Reset I–V curves (symbols) of Au/SLG/ta-C/Pt device with  $d = 20 \mu\text{m}$  in 3 consecutive switching cycles. The I–V curves of HRS1, HRS2, and LRS1 are fitted by the QPC model (line). (b) Fitting parameters  $\omega_x, \omega_y$  as a function of current at 1V.  $V_0 = 0.15 \text{ eV}$  for all cases. (c) Schematic of 4 stages when the device is reset from LRS to HRS.

properties of the bottom and top electrodes,  $T(E)$  is related to the physical dimensions of the constriction.  $T(E)$  decreases with increasing  $\omega_x$  or decreasing  $\omega_y$  [72, 73].

Using equation (1) the fitted I–V curves of the HRS for Au/ta-C/Pt and Au/SLG/ta-C/Pt devices are shown by the solid lines in figure 7(a). This gives  $\omega_x = 1.0 \cdot 10^{15} \text{ Hz}$ ,  $\omega_y = 4.4 \cdot 10^{14} \text{ Hz}$ ,  $V_0 = 0.15 \text{ eV}$ . Reference [72] found similar  $\omega_x = 6 \cdot 10^{14} \text{ Hz}$  and  $\omega_y = 3.8 \cdot 10^{14} \text{ Hz}$  with  $V_0 = 0.25 \text{ V}$  when simulating a TiN/HfO<sub>2</sub>/Pt device, showing that the switching processes based on CF formation and rupture are comparable. Several approximations are made to

simplify the calculations and illustrate the influence of SLG on the leakage current. The DOS for a single sub-band in a quantum well system is approximated by  $\sim m_e^*/\pi\hbar^2$  [77], where  $m_e^*$  is the effective electron mass. For Au,  $m_e^*/m_e = 1.1$  with  $m_e$  the electron mass. This gives  $\text{DOS} \sim 10^{18} \text{ eV}^{-1} \text{ m}^{-2}$  for Au. We thus set the Au DOS to a constant  $\sim 10^{18} \text{ eV}^{-1} \text{ m}^{-2}$ . For SLG we have  $\text{DOS}(E) = 2E/\pi\hbar^2 v_F^2$  [78]. Since the ta-C capacitance  $\sim 0.45 \mu\text{F cm}^{-2}$  is much smaller than that of SLG, the  $E_F$  shift in SLG when a voltage is applied is ignored, as the largest voltage drop is in ta-C.  $E_F$  pinning might happen at the interface of SLG with Au [79], thus the SLG  $E_F$  shift with applied volt-

age may be neglected. Furthermore, the same fitting parameters that describe the constriction part of the CF formed in ta-C, i.e. the CF dimensions, are used for both devices with and without SLG ( $\omega_x = 1.0 \cdot 10^{15}$  Hz,  $\omega_y = 4.4 \cdot 10^{14}$  Hz, and  $V_0 = 0.15$  eV), while the SLG influence in the tunneling part is included by taking the SLG DOS into account to model the I–V curves. With this, the modeled I–V curves of devices without and with SLG match the measured ones, figure 7(a). This indicates that, due to the low SLG DOS near the Dirac point, SLG suppresses tunneling in the metal/ta-C/metal system, especially below 0.5 V, thus increasing  $R_{ON}/R_{OFF}$ . As the voltage increases, the tunneling currents in the devices with and without SLG become closer because, with increasing bias, a higher DOS becomes available in SLG leading to an increase in tunneling or leakage current.

We also observe multiple resistive states in the device with SLG, figure 9. We analyze these with the QPC model. Figure 9(a) plots the measured I–V curves over 3 consecutive RESET processes for the same  $d = 20 \mu\text{m}$ . The SET processes are achieved under the same conditions by sweeping the voltage from 0 to 6 V with  $I_{CC} = 3$  mA. Due to the stochastic nature of the reversible, soft-breakdown, i.e. the CF formation, in the SET process, 3 LRSs can be observed. While LRS2 and LRS3 have a linear I–V relation and are governed by Ohm's law, LRS1 has a non-linear I–V and can be fitted by the QPC model. Two HRSs can be seen in figure 9(a). Although the device is reset to HRS1 in the 1st and 3rd cycle, it is reset to an intermediate HRS2 in the 2nd cycle. Both HRS1 and HRS2 can be fitted by the QPC model, as shown by the black line in figure 9(a). Figure 9(b) plots the fitting parameters used to describe the dimensions of the constriction in LRS1, HRS1 and HRS2. 4 CF representative stages at different resistive states in the RESET process are sketched in figure 9(c). LRS1 corresponds to stage 1: a wide CF. In HRS2,  $\omega_y$  is increased compared to LRS1, which leads to a gradual narrowing of the CF. This indicates a decrease of the CF cross-section, as in stage 2. Furthermore, compared to the fitting parameters for HRS2,  $\omega_x$  at HRS1 is smaller, while  $\omega_y$  remains almost constant. This indicates the decrease of the longitudinal constriction until the CF ruptures, stage 4. This reveals the dynamics of the RESET process. The CF starts to become thinner and then ruptures due to the fuse-effect caused by the strong local Joule heat at  $T > 1500$  K for the SET and between 1500 and 2500 K for RESET [10]. Overall, the QPC model can be used to describe the I–V curves and sheds light on the switching mechanism. It indicates that the reduction in leakage current is due to SLG, paving the way for the development of  $4F^2$  sized cells.

These results show that the tunneling model describes well the I–V curves in figures 7 and 9. We note that our devices include a wet SLG transfer step, which is expected to add contaminations [80]. SLG

was reported to act as tunneling barrier in memory devices based on metal-oxides [40]. Thus, interface cleanliness and prevention of defect states at the interface are not the main reason for the improved  $R_{ON}/R_{OFF}$ .

## 4. Conclusions

We investigated the resistive switching properties of ta-C based MIM devices, including forming-free process, polarity-independent operation, ON/OFF ratio and power density. We showed that, by adopting graphene-based electrodes, the ON/OFF ratio is improved by one order of magnitude without increasing the switching power. We attribute the underlying mechanism to a suppressed tunneling current due to the low DOS of graphene near the Dirac point. We also demonstrated the capability of multilevel storage. This paves the way for RRAMs integrated in crossbar arrays without need of an access transistor, and the development of  $4F^2$  cells.

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